Lecture 12

Multiple Linear Regression

DSC 40A, Fall 2024

Agenda

- Recap: regression and linear algebra
- Multiple linear regression.
- Interpreting parameters.

Recap: Regression and linear algebra

Regression and linear algebra (Solution 1)

• Define the design matrix $X \in \mathbb{R}^{n \times 2}$, observation vector $\vec{y} \in \mathbb{R}^n$, and parameter vector $\vec{w} \in \mathbb{R}^2$ as:

$$X = \begin{bmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_n \end{bmatrix} \qquad \vec{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} \qquad \vec{w} = \begin{bmatrix} w_0 \\ w_1 \end{bmatrix} \quad \text{ordercept}$$

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• How do we make the hypothesis vector, $\vec{h} = X\vec{w}$, as close to \vec{y} as possible? Use the parameter vector \vec{w}^* :

$$ec{w}^* = (X^T X)^{-1} X^T ec{y}$$

• Solution: We chose \vec{w}^* so that $\vec{h}^* = X\vec{w}^*$ is the projection of \vec{y} onto the span of the columns of the design matrix, X and minimized the length of the projection error $\|\vec{e}\| = \|\vec{y} - X\vec{w}\|$.

Regression and linear algebra (Solution 2)

• Define the design matrix $X \in \mathbb{R}^{n \times 2}$, observation vector $\vec{y} \in \mathbb{R}^n$, and parameter vector $\vec{w} \in \mathbb{R}^2$ as:

$$X = \begin{bmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_n \end{bmatrix} \qquad \vec{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ \vdots \\ y_n \end{bmatrix} \qquad \vec{w} = \begin{bmatrix} w_0 \\ w_1 \end{bmatrix} \qquad \text{intersept}$$

• How do we minimize the mean squared error $R_{
m sq}(\vec{w}) = \frac{1}{n} ||\vec{y} - X\vec{w}||^2$? Using calculus the optimal paramter vector \vec{w}^* is:

$$ec{w}^* = (X^T X)^{-1} X^T ec{y}$$

• Solution: we computed the gradient of $R_{sq}(\vec{w})$, set it to zero and solved for \vec{w} . $\sqrt{R_{sq}(c)} = 0 \rightarrow \sqrt{t}$

Multiple linear regression

				G
	X departure_hour	day_of_month	m	inutes
0	10.816667	15		68.0
1	7.750000	16		94.0
2	8.450000	22		63.0
3	7.133333	23		100.0
4	9.150000	30		69.0
•••				

So far, we've fit **simple** linear regression models, which use only **one** feature ('departure_hour') for making predictions.

Incorporating multiple features

• In the context of the commute times dataset, the simple linear regression model we fit was of the form:

pred. commute = H(departure hour)

 $= w_0 + w_1 \cdot \text{departure hour}$

- Now, we'll try and fit a <u>multiple</u> linear regression model of the form: pred. commute = H(departure hour)= $w_0 + w_1 \cdot \text{departure hour} + w_2 \cdot \text{day of month}$
- Linear regression with **multiple** features is called **multiple linear regression**.
- How do we find w_0^* , w_1^* , and w_2^* ? Hypothesis : multiple linear regression rodul loss : squared error Ly use normal equations

Geometric interpretation

• The hypothesis function:

```
H(	ext{departure hour}) = w_0 + w_1 \cdot 	ext{departure hour}
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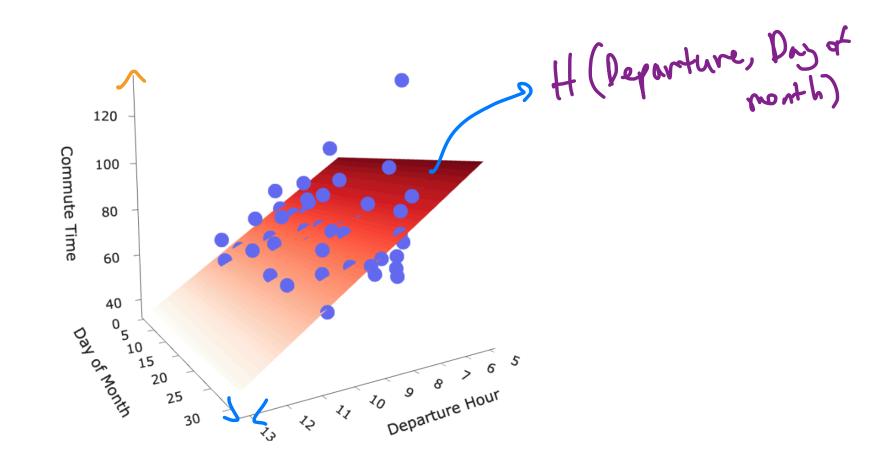
looks like a line in 2D.

- Questions:
 - How many dimensions do we need to graph the hypothesis function:
 $H(\text{departure hour}) = w_0 + w_1 \cdot \text{departure hour} + w_2 \cdot \text{day of month}$
 - What is the shape of the hypothesis function?

$$Z = a_X + b_y + c$$

 $\implies plane$

Commute Time vs. Departure Hour and Day of Month

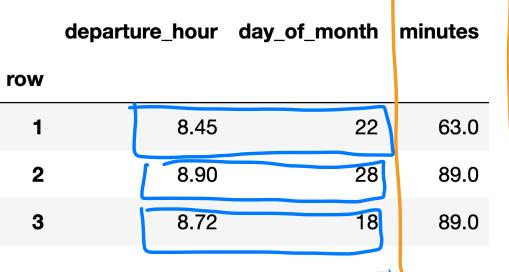


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Our new hypothesis function is a **plane** in 3D! Our goal is to find the **plane** of best fit that pierces through the cloud of points.

The setup

• Suppose we have the following dataset.



• We can represent each day with a **feature vector**, \vec{x} :



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The hypothesis vector

prediction Lesign Parameter vector • When our hypothesis function is of the form: matrix

 $H(\text{departure hour}) = w_0 + w_1 \cdot \text{departure hour} + w_2 \cdot \text{day of month}$

the hypothesis vector $\vec{h} \in \mathbb{R}^n$ can be written as: $\vec{h} = \begin{bmatrix} H(\text{departure hour}_1, \text{day}_1) \\ H(\text{departure hour}_2, \text{day}_2) \\ \dots \\ H(\text{departure hour}_n, \text{day}_n) \end{bmatrix} = \begin{bmatrix} 1 & \text{departure hour}_1 & \text{day}_1 \\ 1 & \text{departure hour}_2 & \text{day}_2 \\ \dots & \dots & \dots \\ 1 & \text{departure hour}_n & \text{day}_n \end{bmatrix} \begin{bmatrix} w_0 \\ w_1 \\ w_2 \end{bmatrix}$ $\left[\left(\begin{array}{c} departure \ hour_{2}, \ day_{2} \right) = & & \\ \left(\begin{array}{c} departure \ hour_{2}, \ day_{2} \right) = & \\ W_{0} \end{array} \right) = & \\ W_{0} + & W_{1} \ departure \ hour_{2} + & \\ W_{2} \cdot & \\ W_{2} \cdot & \\ W_{2} \cdot & \\ \end{array} \right) = & \\ W_{0} + & W_{1} \ departure \ hour_{2} + & \\ W_{2} \cdot & \\ \end{array} \right)$

$\chi \vec{\rho} = 0$

Finding the optimal parameters

• To find the optimal parameter vector, $ec{w}^*$, we can use the design matrix $X\in \mathbb{R}^{n imes 3}$ and observation vector $\vec{y} \in \mathbb{R}^n$:

 $X = \begin{bmatrix} 1 & \text{departure hour}_1 & \text{day}_1 \\ 1 & \text{departure hour}_2 & \text{day}_2 \\ \dots & \dots & \dots \\ 1 & \text{departure hour}_n & \text{day}_n \end{bmatrix} \qquad \vec{y} = \begin{bmatrix} \text{commute time}_1 \\ \text{commute time}_2 \\ \vdots \\ \text{commute time}_n \end{bmatrix}$

• Then, all we need to do is solve the **normal equations**: $X^T X \vec{w}^* = X^T \vec{y}$ $\vec{v} \in \begin{bmatrix} v_0 \\ v_1 \\ w_2 \end{bmatrix}$ If $X^T X$ is invertible, we know the solution is:

$$ec{w}^* = (X^T X)^{-1} X^T ec{y}$$

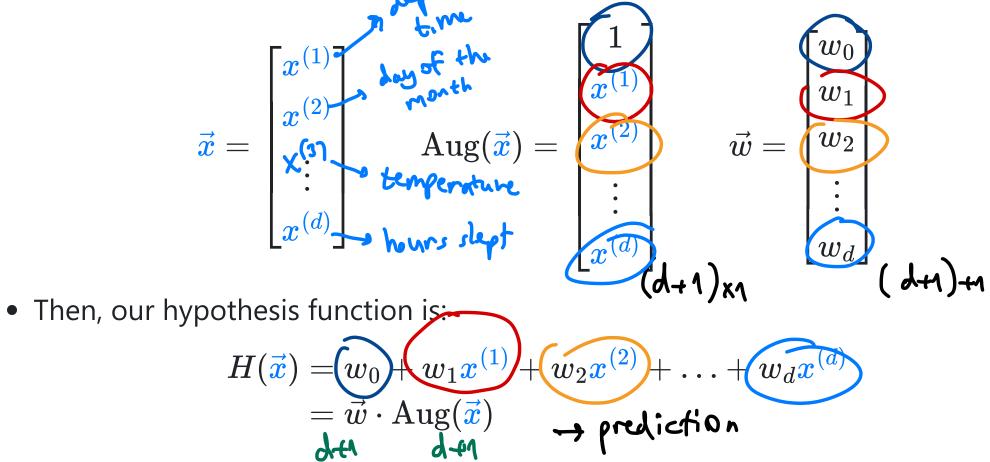
$\chi_n - \Lambda_{st} data point$ Notation for multiple linear regression $\chi_n^{(n)} - 1_{st}$ feature in my data

- We will need to keep track of multiple features for every individual in our dataset.
 - In practice, we could have hundreds or thousands of features!
- As before, subscripts distinguish between individuals in our dataset. We have *n* individuals, also called **training examples**.
- departure hour: $x^{(1)} \in \mathbb{R}^{n}$ day of month: $x^{(2)} \in \mathbb{R}^{n}$ Think of $x^{(1)}$, $x^{(2)}$, ... as new variable names, like new letters. (column of X) not exponent (7) the value of the 7th feature X_{4} for the 4ch data point (row of X)

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Augmented feature vectors

• The **augmented feature vector** $\operatorname{Aug}(\vec{x})$ is the vector obtained by adding a 1 to the front of feature vector \vec{x} :



The general problem

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• We have *n* data points, $(\vec{x}_1, y_1), (\vec{x}_2, y_2), \dots, (\vec{x}_n, y_n)$, where each \vec{x}_i is a feature vector of *d* features:

Simple linear regression dataset (x,y) (X,yn), (X,yz) ...(Xn,yn) X; ElR scalars

• We want to find a good linear hypothesis function:

$$egin{aligned} H(ec{x}) &= w_0 + w_1 x^{(1)} + w_2 x^{(2)} + \ldots + w_d x^{(d)} \ &= ec{w} \cdot \operatorname{Aug}(ec{x}) \ & ext{How do we find $v_{o'}$, v_1, w_2, $\ldots, w_d}, \end{aligned}$$

 $ec{x_i} = egin{bmatrix} x_i^{(1)} \ x_i^{(2)} \ ec{x}_i^{(d)} \ ec{\epsilon} \ ec{k}^{igstarrow} \end{array}$

The general solution

- Define the design matrix $X \in \mathbb{R}^{n \times (d+1)}$ and observation vector $\vec{y} \in \mathbb{R}^{n}$: **datapoint** i $X = \begin{bmatrix} 1 & x_1^{(1)} & x_1^{(2)} & \dots & x_1^{(d)} \\ 1 & x_2^{(1)} & x_2^{(2)} & \dots & x_2^{(d)} \\ \vdots & \vdots & \vdots & \vdots \\ 1 & x_n^{(1)} & x_n^{(2)} & \dots & x_n^{(d)} \end{bmatrix} = \begin{bmatrix} \operatorname{Aug}(\vec{x_1})^T \\ \operatorname{Aug}(\vec{x_2})^T \\ \vdots \\ \operatorname{Aug}(\vec{x_n})^T \end{bmatrix} \quad \vec{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$
 - Then, solve the **normal equations** to find the optimal parameter vector, \vec{w}^* :

$$X^T X \vec{w}^* = X^T \vec{y}$$

Terminology for parameters

- With d features, $ec{w}$ has d+1 entries.
- w_0 is the **bias**, also known as the **intercept**.
- w_1, w_2, \ldots, w_d each give the **weight**, or **coefficient**, or **slope**, of a feature.

$$H(ec{x}) = w_0 + w_1 x^{(1)} + w_2 x^{(2)} + \ldots + w_d x^{(d)}$$

Interpreting parameters

Example: Predicting sales

- For each of *M* stores, we have:
 - net sales,
 - square feet,
 - inventory,
 - advertising expenditure,
 - district size, and
 - number of competing stores.
- Goal: Predict net sales given the other five features.
- To begin, we'll start trying to fit the hypothesis function to predict sales: $H(ext{square feet}, ext{competitors}) = w_0 + w_1 \cdot ext{square feet} + w_2 \cdot ext{competitors}$



Answer at q.dsc40a.com

$$H(ext{square feet, competitors}) = w_0 + w_1 \cdot ext{square feet} + w_2 \cdot ext{competitors}$$

What will be the signs of w_1^* and w_2^* ?

• A.
$$w_1^* + w_2^* +$$

• B. $w_1^* + w_2^* -$
• A. $w_1^* - w_2^* +$
• A. $w_1^* - w_2^* -$

Let's find out! Follow along in this notebook.



Answer at q.dsc40a.com

Which feature is most "important"?

- A. square feet: $w_1^* = 16.202$
- B. competitors: $w_2^* = -5.311$
- C. inventory: $w_2^*=0.175$
- D. advertising: $w_3^* = 11.526$
- + E. district size: $w_4^* = 13.580$

(not features are most "important"? $5 (100 \text{ Jobs}) = \frac{5}{(274)} (100 \text{ Jobs})$

- The most important feature is **not necessarily** the feature with largest magnitude weight.
- Features are measured in different units, i.e. different scales.
 - $^\circ\,$ Suppose I fit one hypothesis function, H_1 , with sales in US dollars, and another hypothesis function, H_2 , with sales in Japanese yen (1 USD pprox 157 yen).
 - Sales is just as important in both hypothesis functions.
 - $^{\circ}\,$ But the weight of sales in H_1 will be 157 times larger than the weight of sales in H_2 .
- Solution: If you care about the interpretability of the resulting weights, standardize each feature before performing regression, i.e. convert each feature to standard units.

Standard units

• Recall: to convert a feature x_1, x_2, \ldots, x_n to standard units, we use the formula:

$$x_{i\;(\mathrm{su})} = rac{x_i - ar{x}}{\sigma_x}$$

• Example: 1, 7, 7, 9.

• Mean:
$$\frac{1+7+7+9}{4} = \frac{24}{4} = 6.$$

• Standard deviation:

$$SD = \sqrt{\frac{1}{4}((1-6)^2 + (7-6)^2 + (7-6)^2 + (9-6)^2)} = \sqrt{\frac{1}{4} \cdot 36} = 3$$

• Standardized data:

$$1 \mapsto \frac{1-6}{3} = \boxed{-\frac{5}{3}} \qquad 7 \mapsto \frac{7-6}{3} = \boxed{\frac{1}{3}} \qquad 7 \mapsto \boxed{\frac{1}{3}} \qquad 9 \mapsto \frac{9-6}{3} = \boxed{1}_{24}$$

Standard units for multiple linear regression

- The result of standardizing each feature (separately!) is that the units of each feature are on the same scale.
 - There's no need to standardize the outcome (net sales), since it's not being compared to anything.
 - Also, we can't standardize the column of all 1s.
- Then, solve the normal equations. The resulting $w_0^*, w_1^*, \ldots, w_d^*$ are called the **standardized regression coefficients**.
- Standardized regression coefficients can be directly compared to one another.
- Note that standardizing each feature **does not** change the MSE of the resulting hypothesis function!

Once again, let's try it out! Follow along in this notebook.

Summary

- The normal equations can be used to solve multiple linear regression problems.
- Interpret the parameters as weights. Signs give meaningful information. Can only compare weight magnitude if data is standardized.
- On Friday: nonlinear features!